

## **Reminders 04-15-10:**

- POW 10 Due next Thursday**
- Chapter 10 and 11 quiz in class next Tuesday**

## **Objectives**

- Formal Definition of Torque**
- Formal Definition of Angular Momentum**
- Relation Between Torque and Angular Momentum**

### Example:

If a force  $\mathbf{F} = (3 \mathbf{i} + 2 \mathbf{k})$  N is applied at the position  $\mathbf{r} = (1 \mathbf{i} - 2 \mathbf{j})$  m what is the torque due to the force?

$$\begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & -2 & 0 \\ 3 & 0 & 2 \end{vmatrix} = \hat{i} \begin{vmatrix} -2 & 0 \\ 0 & 2 \end{vmatrix} + \dots$$

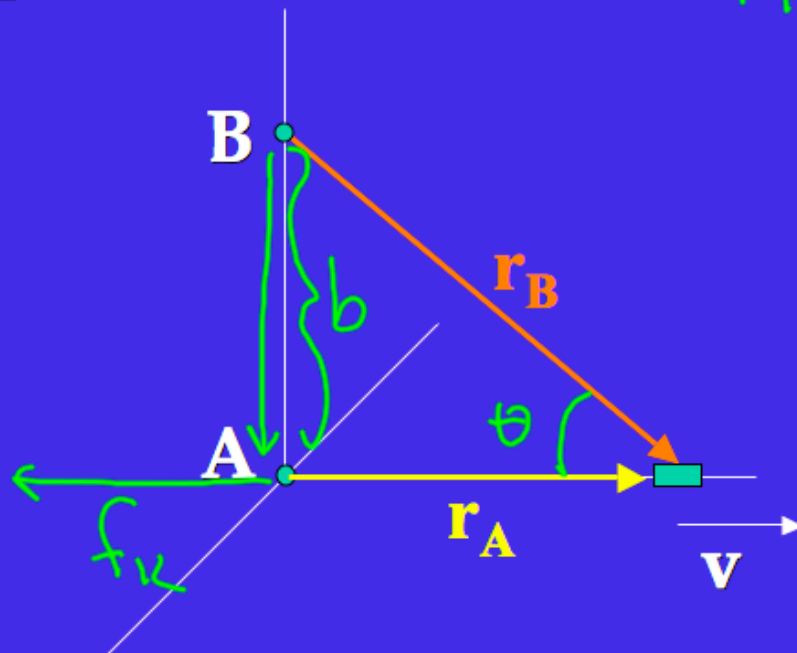
ith component is  $-4\hat{i}$

$$-\hat{j} \begin{vmatrix} 1 & 0 \\ 3 & 2 \end{vmatrix} = -2\hat{j}$$

$$\hat{k} \begin{vmatrix} 1 & -2 \\ 3 & 0 \end{vmatrix} = 6\hat{k}$$

$$\vec{\tau} = -4\hat{i} - 2\hat{j} + 6\hat{k}$$

Consider a particle of mass  $m$  moving along the  $x$ -axis. The only force acting on it is kinetic friction. Calculate the torque about points A and B (a distance  $b$  above point A).



$$f_k \parallel \vec{r}_b \sin \theta$$

$$\left| \sum \vec{\tau}_A \right| = \left| \vec{r}_A \times \vec{f}_k \right| =$$

$$\left| \sum \vec{\tau}_B \right| = \left| \vec{r}_B \times \vec{f}_k \right| =$$

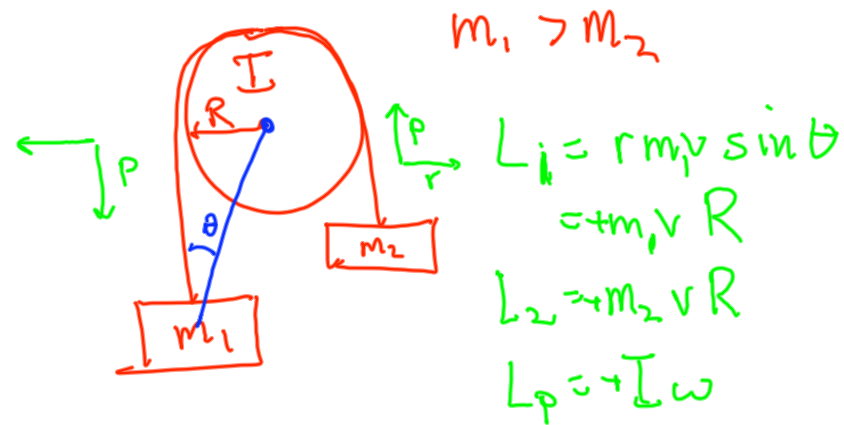
Notice that the sum of the torques depends on the choice of origin. However, it can be shown that if the net force on an object is zero then the sum of the torques will be the same regardless of the choice of origin.

**Example**  
The position of a particle of mass 3 kg is given by  $\vec{r} = (6 \hat{i} + 8t \hat{j})$  m. Determine the angular momentum of the particle about the origin as a function of time.

$$\vec{L} = \vec{r} \times \vec{p} = \vec{r} \times m\vec{v}$$

$$\vec{v} = \frac{d\vec{r}}{dt} = 8 \hat{j}$$

$$\begin{aligned} \vec{L} &= (6 \hat{i} + 8t \hat{j}) \times (24 \hat{j}) \\ &= 144 \hat{k} \text{ Kg m}^2/\text{s} \end{aligned}$$



$$\rightarrow L_{\text{system}} = (m_1 + m_2) v R + I \omega$$

$$F_{\text{ext}} = m_1 g - m_2 g = (m_1 - m_2) g$$

$$\tau_{\text{ext}} = (m_1 - m_2) g R = \frac{dL}{dt}$$

$$\frac{dL_{\text{system}}}{dt} = (m_1 + m_2) a R + I \alpha$$

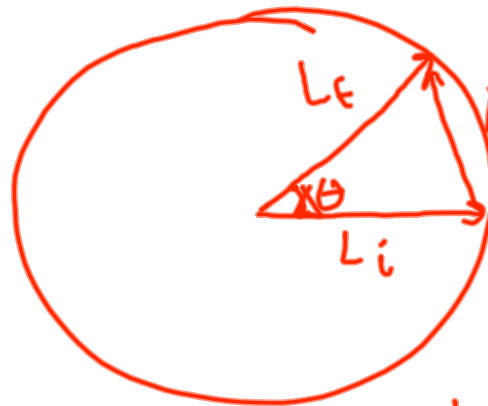
$$(m_1 - m_2) g R = (m_1 + m_2) a R + I \alpha$$

$$= (m_1 + m_2) a R + I \frac{a}{R}$$

$$(m_1 - m_2) g = \left[ (m_1 + m_2) + \frac{I}{R^2} \right] a$$

$$a = \frac{(m_1 - m_2) g}{m_1 + m_2 + I/R^2}$$

Calculate precessional freq.  
of gyroscope.



$$|L_i| = |L_f| = I\omega$$

$\Delta L$  w/  $\Delta\theta$  be  
small  
arc length  
swept out in  
time  $\Delta t$  is  $L_i \Delta\theta$

arc length =  $\Delta L$  for small  $\Delta\theta$

$$\frac{\Delta L}{\Delta t} = L_i \frac{\Delta\theta}{\Delta t}$$

$$\frac{\Delta L}{\Delta t} = I\omega\Omega = mgR$$

$$\Omega = \frac{mgR}{I\omega} \quad \text{valid as long as}$$

as  $\omega \gg \Omega$